











indicates main circuit o indicates control circuit

Notes:

- *1: The main circuit of 200V 1~25HP and 400V 1~30HP (included) with built-in braking transistor provide terminal B2. The braking resistor can be connected directly between B1 and B2. Optional braking module is available for the other models.
- *2: The multi-function digital input terminals \$1~\$8 can be set to Source (PNP) or Sink (NPN) mode by \$W3.
- *3: Multi-function analog input 2 (Al2) can be set to the voltage command input (0~10/-10~10v) or the current command input (4~20mA) through SW2.
- *4: When integrated safety function is NOT used, connect a link across terminals F1 & F2 for the inverter output to function. External safety circuits can be interfaced with inverter using terminals F1 and F2.
- *5: Terminals -12V, R2A-R2C and PO-GND are provided for 200V 3HP and 400V 5HP ratings or above.
- *6: Terminals DO2 and DOE are provided for 200V 2HP and 400V 3HP ratings or below.

BASIC SPECIFICATIONS

200V Class

In	verter C	Capacity (HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125	150
	HD*3	Rated Output Capacity (KVA)	1.9	3	4.2	6.7	9.5	12.6	17.9	22.9	27.8	32.4	43.8	55.3	68.6	81.9	108	132	158
		Rated Output Current (A)	5	8	11	17.5	25	33	47	60	73	85	115	145	180	215	283	346	415
*2		Maximum Applicable Motor*1 HP (KW)	1 (0.75)	2 (1.5)	3 (2.2)	5 (3.7)	7.5 (5.5)	10 (7.5)	15 (11)	20 (15)	25 (18.5)	30 (22)	40 (30)	50 (37)	60 (45)	75 (55)	100 (75)	125 (90)	150 (110)
Ratin	ND*4	Rated Output Capacity (KVA)	2.3	3.7	4.6	8.0	11.4	15.2	21.3	26.3	30.1	41.9	52.6	64.4	76.2	95.3	118.9	137.2	172
Output Rating 🚴		Rated Output Current (A)	6	9.6	12	21	30	40	56	69	79	110	138	169	200	250	312	400	450
O		Maximum Applicable Motor*1 HP (KW)	1.5 (1.1)	3 (2.2)	4 (3)	7.5 (5.5)	10 (7.5)	15 (11)	20 (15)	25 (18.5)	30 (22)	40 (30)	50 (37)	60 (45)	75 (55)	100 (75)	125 (90)	150 (110)	175 (130)
	Maximu	Three-Phase, 200V to 240V																	
	Maximum	Output Frequency (Hz)	Based on parameter setting 0.1~400.0 (1200.0) Hz																
Input Power	Rated Voltage, Frequency		Single/Three- Phase,200V to Three-Phase, 200V to 240V, 50/60Hz 240V, 50/60Hz																
Inpu	Allowabl	e Voltage Fluctuation	-15% ~ +10%																
	Allowable Frequency Fluctuation										±5%								
	Braking Transistor		Built-in Option (Braking Module)																
Frame Size		1		2	2	į	3		4			5	6		7	7	8	3	

400V Class

li	verter C	Capacity (HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125	150	175	215	250	300	375	425
*2 D		Rated Output Capacity (KVA)	2.6	3.2	4.2	7	11.3	13.7	18.3	23.6	29.7	34.3	45.7	57.2	69.3	89.9	114	137	165	198	225	282	343	400	461
	HD*3	Rated Output Current (A)	3.4	4.2	5.5	9.2	14.8	18	24	31	39	45	60	75	91	118	150	180	216	260	295	370	450	523	585
		Maximum Applicable Motor*1 HP (KW)	1 (0.75)	2 (1.5)	3 (2.2)	5 (4)	7.5 (5.5)	10 (7.5)	15 (11)	20 (15)	25 (18.5)	30 (22)	40 (30)	50 (37)	60 (45)	75 (55)	100 (75)	125 (90)	150 (110)	175 (132)	215 (160)	250 (185)	300 (220)	375 (280)	425 (315)
Ratir		Rated Output Capacity (KVA)	3.1	4.1	5.3	8.5	13.3	17.5	23.6	29.0	33.5	44.2	54.9	67.1	78.5	111	126	159	191	226	250	332	393	446	446
Output Rating _{&}	ND*4	Rated Output Current (A)	4.1	5.4	6.9	11.1	17.5	23	31	38	44	58	72	88	103	145	165	208	250	296	328	435	515	585	585
		Maximum Applicable Motor*1 HP (KW)	2 (1.5)	3 (2.2)	4 (3)	7.5 (5.5)	10 (7.5)	15 (11)	20 (15)	25 (18.5)	30 (22)	40 (30)	50 (37)	60 (45)	75 (55)	100 (75)	125 (90)	150 (110)	175 (132)	215 (160)	250 (185)	270 (200)	335 (250)	425 (315)	425 (315)
	Maximum Output Voltage (V)			Three-Phase, 380V to 480V																					
	Maximum Output Frequency (Hz)			Based on parameter setting 0.1~400.0(1200.0) Hz																					
wer	Rated Voltage, Frequency			Three-Phase, 380V to 480V, 50/60Hz																					
ot Po	Rated Voltage, Frequency Allowable Voltage Fluctuation												-159	% ~ +	10%										
Allowable Frequency Fluctuation														±5%											
	Braking Transistor			Built-in Option (Braking Module)																					
Frame Size				1		2	2	(3		4			5		(3		7				8	3	

Notes:

- *1. Based on the standard 4-pole induction motor. The selected inverter must have a higher output current rating than the motor.
- *2. The default setting of A510 takes HD (heavy duty mode) as the base. To switch A510 to ND (normal duty mode) set parameter (00-27) to 1.
- *3. The default setting of carrier frequency in HD mode is shown in right side table, if the setting value is higher than default setting, de-rating may be required.
- *4. The default setting of carrier frequency in ND mode is 2kHz, if the setting value is higher than default setting, de-rating may be required.
- *5. If control mode is set to SLV mode and maximum frequency is larger than 80Hz, the carrier frequency range is 2~8kHz.

Inverter Voltage	e and Capacity	HD mode carrier	HD mode carrier freq default setting				
200V class	400V class	freq range					
1~20HP	1~30HP	2~16kHz	8kHz				
25HP	-	2~12kHz	6kHz				
30~40HP	40~50HP	2~12kHz*5	5kHz				
50~100HP	60~175HP	2~10kHz*5	5kHz				
-	215HP	2~8kHz	3kHz				
125~150HP	-	2~5kHz	5kHz				
	250~375HP	2~5kHz	4kHz				
	425HP	2~5kHz	2kHz				

	Display	LED keypad with 5-digits seven-segment display (LCD keypad option)									
	Control Modes	V/F, V/F+PG, SLV, SV, PMSV, PMSLV ^{*1} (SVPWM Modulation)									
	Output Frequency	0.1Hz~400.0Hz ²									
	Frequency Accuracy	Digital references: ±0.01%(-10 to +40°C), Analog references: ±0.1% (25°C ±10°C)									
	Speed Control Accuracy	±0.1%(Sensor Vector Control Mode, SV) ¹³ , ±0.5%(Sensorless Vector Control Mode, SLV) ¹³									
	Frequency Setting Resolution	Digital References: 0.01Hz, Analog References: 0.06Hz at 60Hz									
	Output Frequency Resolution	0.01Hz									
Control Characteristics	Overload Tolerance	Heavy Duty Mode (HD.): 150% rated current for 60sec, 200% rated current for 2 sec. (Factory default) Normal Duty Mode (ND.): 120% rated current for 60sec									
ara	Frequency Setting Signal	0 to +10V , 4 to 20mA, -10V to +10V or pulse train input									
ਨੂ	Acceleration / Deceleration Time	0.0 \sim 6000.0 sec (separately set acceleration and deceleration time)									
ntro	Voltage / Frequency Characteristics	15 fixed and one customized v/f pattern									
ပိ	Braking Torque	Approximate 20%									
	Main Control Functions	Auto Tuning, Zero Servo, Torque Control, Position Control, Droop, Soft-PWM, Over-Voltage Protection, Dynamic Braking, Speed Search, Frequency Traversing, Momentary Power Loss Restart, PID Control, Automatic Torque Compensation, Slip Compensation, RS-485 Communication, Close Loop Control with PG, Simple PLC Function ⁻¹ , Two Analog Output, Safety input contact									
	Other Functions	Records of Power ON and Operation Time, Four Fault History Records and Latest Fault State Record Energy-Saving Function, Phase Loss Protection, DC Braking, Dwell, S Curve Acceleration and Deceleration Up / Down Operation, Modbus Communication Protocol, Output of Pulse Multiple, Display of Engineering Unit, SINK / SOURCE Selection									
	Stall Prevention	Current level can be adjusted. (In acceleration or constant speed, it can be set separately. In deceleration, it can be set with or without stall protection)									
	Over Current (OC) and Output Short-Circuit (SC) Protection	It stops when the current exceeds 200% of the inverter rated current.									
ions	Inverter Overload Protection (OL2)	Inverter will be stopped when the output is higher than below conditions. Heavy Duty Mode (HD.): 150% rated current for 60sec, 200% rated current for 2 sec. (Factory default), Carrier frequency is from 2kHz to 8kHz. Normal Duty Mode (ND.): 120% rated current for 60sec, Carrier frequency is 2kHz.									
Juct	Motor Overload Protection (OL1)	Electrical overload protection curve									
Protection Functions	Over Voltage Protection (OV)	If the main circuit DC voltage is over 410V (200V class) / 820V (400V class), the motor stops running.									
ecti	Under Voltage (UV)	If the main circuit DC voltage is under 190V (200V class) / 380V (400V class), the motor stops running.									
Prof	Momentary Power Loss Restart	Power loss exceeds 15ms You can set the function of momentary power loss restart to up to 2 sec									
	Overheat Protection (OH)	Thermistor sensor on heatsink									
	Ground Fault Protection (GF)	Protection by current detection circuit									
	Charge Indicator	When main circuit DC voltage ≧50V, the CHARGE LED is on.									
	Output Phase Loss Protection (OPL)	If the OPL function acts, the motor stops rotation automatically									
	Location	Indoor (Protected from corrosive gases and dust)									
ent	Ambient Temperature	-10 to +40°C without de-rating (IP20/NEMA1), -10 to +50°C (IP00), with de-rating, its maximum operation temperature is 60° C									
ifica	Storage Temperature	-20~+70°C									
Environment Specification	Humidity	95%RH or less (no condensation)									
SPE	Altitude and Vibration	Altitude of 1000 meters or lower; 1.0G, in compliance with IEC 60068-2-6									
Cor	mmunication Function	Built-in RS-485 as standard (Modbus protocol with standard RJ45)									
Elec	ctromagnetic Interference (EMI)	In compliance with EN61800-3 standard, 400V 60HP or below can be built in.									
	ctromagnetic Compatibility (EMS)	In compliance with EN61800-3 standard									
	tification UL	In compliance with EN61800-3 (CE & RE) and EN61800-5-1 (LVD) UL508C									
Ont	iion Card	Open collector type(IM), line driver type(IM) and Line driver type for PM motor									
Opi	non Gara	open concern, peting, and arrest speting and area type for twittering									

Notes:

- *1. PM sensorless(PMSLV) control mode is under development.
- *2. The maximum output frequency of each control modes is different, please read user manual for more details.
- *3. Speed control accuracy will be influenced when the motor and installation condition are different.
- *4. The A510 dedicated model is not built-in this function.